

# Undermodelling Detection with Sign-Perturbed Sums Algo Carè <sup>1,2</sup> Marco Campi <sup>3</sup> Balázs Csáii <sup>2</sup> Erik Wever <sup>4</sup>

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- I. Introduction
- II. Standard SPS for Linear Regression
- III. SPS with Undermodelling Detection
- IV. Numerical Experiments
- V. Summary and Conclusions



## Motivations

- SPS (Sign-Perturbed Sums) builds confidence regions around the LS (least squares) estimate of linear regression problems.
- Only mild statistical assumptions are needed, e.g., symmetry.
- Not needed: stationarity, moments, particular distributions.
- SPS has many nice properties (as we will see later), most importantly its confindence regions are exact.
- Regarding the models, the assumption of SPS is that the true system generating the observations is in the model class.
- However, if the model class is wrong, SPS cannot detect it.
- Here, we suggest an extension of SPS, UD-SPS, that still builds exact confidence sets, if the model is correct, but can also detect, in the long run, if the system is undermodelled.



## Linear Regression

#### Consider a standard linear regression problem:

## Linear Regression

$$y_t \triangleq \varphi_t^{\mathrm{T}} \theta^* + w_t$$

#### where

$$y_t$$
 — output (for time  $t = 1, ..., n$ )  
 $\varphi_t$  — regressor (exogenous,  $d$  dimensional)  
 $w_t$  — noise (independet, symmetric)  
 $\theta^*$  — true parameter (deterministic,  $d$  dimensional)  
 $\Phi_n = [\varphi_1, ..., \varphi_n]^T$  — skinny and full rank



## Least Squares

Given: a sample, Z, of size *n* of outputs  $\{y_t\}$  and regressors  $\{\varphi_t\}$ A classical approach is to minimize the least squares criterion

$$\mathcal{V}(\theta \mid \mathcal{Z}) \triangleq \frac{1}{2} \sum_{t=1}^{n} (y_t - \varphi_t^{\mathrm{T}} \theta)^2.$$

The least squares estimate (LSE) can be found by solving

Normal Equation

$$\nabla_{\theta} \mathcal{V}(\hat{\theta}_{n} \mid \mathcal{Z}) = \sum_{t=1}^{n} \varphi_{t}(y_{t} - \varphi_{t}^{\mathrm{T}} \hat{\theta}_{n}) = 0$$



## **Confidence Ellipsoids**

LSE is asymptotically normal (under some technical conditions)

$$\sqrt{n}\,(\hat{ heta}_n- heta^*) \stackrel{d}{\longrightarrow} \mathcal{N}(0,\sigma^2\,R^{-1}) \ \ ext{as} \ \ n o\infty,$$

where R is the limit of  $R_n = \frac{1}{n} \sum_{t=1}^n \varphi_t \varphi_t^T$  as  $n \to \infty$  (if exists).

#### Confidence Ellipsoid

$$\widetilde{\Theta}_{n,\mu} \triangleq \left\{ \theta \in \mathbb{R}^d \, : \, (\theta - \hat{\theta}_n)^{\mathrm{T}} \, R_n \left( \theta - \hat{\theta}_n \right) \, \leq \, \frac{\mu \, \hat{\sigma}_n^2}{n} \right\}$$

where  $\mathbb{P}(\theta^* \in \widetilde{\Theta}_{n,\mu}) \approx F_{\chi^2(d)}(\mu)$ , where  $F_{\chi^2(d)}$  is the CDF of  $\chi^2(d)$ ,  $\hat{\sigma}_n^2 \triangleq \frac{1}{n-d} \sum_{t=1}^n (y_t - \varphi_t^{\mathrm{T}} \hat{\theta}_n)^2$ , is an estimate of  $\sigma^2$ .



## Reference and Sign-Perturbed Sums

Let us introduce a reference sum and m - 1 sign-perturbed sums.

#### Reference Sum

$$S_0(\theta) \triangleq R_n^{-\frac{1}{2}} \sum_{t=1}^n \varphi_t(y_t - \varphi_t^{\mathrm{T}}\theta)$$

## Sign-Perturbed Sums

$$S_i(\theta) \triangleq R_n^{-\frac{1}{2}} \sum_{t=1}^n \varphi_t \alpha_{i,t}(y_t - \varphi_t^{\mathrm{T}} \theta)$$

for i = 1, ..., m - 1, where  $\alpha_{i,t}$  (t = 1, ..., n) are i.i.d. random signs, that is  $\alpha_{i,t} = \pm 1$  with probability 1/2 each (Rademacher).



## Intuitive Idea: Distributional Invariance

Recall:  $\{w_t\}$  are independent and each  $w_t$  is symmetric about zero. Observe that, if  $\theta = \theta^*$ , we have (i = 1, ..., m - 1)

#### Distributional Invariance

$$S_0(\theta^*) = R_n^{-\frac{1}{2}} \sum_{t=1}^n \varphi_t w_t$$
  
$$S_i(\theta^*) = R_n^{-\frac{1}{2}} \sum_{t=1}^n \varphi_t \alpha_{i,t} w_t$$

Consider the ordering  $||S_{(0)}(\theta^*)||^2 \prec \cdots \prec ||S_{(m-1)}(\theta^*)||^2$ Note: relation " $\prec$ " is the canonical "<" with random tie-breaking All orderings are equally probable! (they are conditionally i.i.d.)



## Intuitive Idea: Reference Dominance

What if  $\theta \neq \theta^*$ ?

In fact, the reference paraboloid  $||S_0(\theta)||^2$  increases faster than  $\{||S_i(\theta)||^2\}$ , thus will eventually dominate the ordering.

Intuitively, for "large enough"  $\|\tilde{\theta}\|$ , where  $\tilde{\theta} \triangleq \theta^* - \theta$ 

#### Eventual Dominance of the Reference Paraboloid

$$\left\|\sum_{t=1}^{n}\varphi_{t}\varphi_{t}^{\mathrm{T}}\tilde{\theta}+\sum_{t=1}^{n}\varphi_{t}w_{t}\right\|_{R_{n}^{-1}}^{2}>\left\|\sum_{t=1}^{n}\pm\varphi_{t}\varphi_{t}^{\mathrm{T}}\tilde{\theta}+\sum_{t=1}^{n}\pm\varphi_{t}w_{t}\right\|_{R_{n}^{-1}}^{2}$$

with "high probability" (for simplicity  $\pm$  is used instead of  $\{\alpha_{i,t}\}$ ).



## Non-Asymptotic Confidence Regions

The rank of  $||S_0(\theta)||^2$  in the ordering of  $\{||S_i(\theta)||^2\}$  w.r.t.  $\prec$  is

$$\mathcal{R}(\theta) = 1 + \sum_{i=1}^{m-1} \mathbb{I}(\|S_i(\theta)\|^2 \prec \|S_0(\theta)\|^2),$$

where  $\mathbb{I}(\cdot)$  is an indicator function.

Sign-Perturbed Sums (SPS) Confidence Regions

$$\widehat{\Theta}_n \triangleq \left\{ \, heta \in \mathbb{R}^d \, : \, \mathcal{R}(\, heta \,) \leq m - q \, 
ight\}$$

where m > q > 0 are user-chosen integers (design parameters).



# Exact Confidence

(A1) {w<sub>t</sub>} is a sequence of independent random variables.
Each w<sub>t</sub> has a symmetric probability distribution about zero.
(A2) The outer product of regressors is invertible, det(R<sub>n</sub>) ≠ 0.

Exact Confidence of SPS

$$\mathbb{P}\big(\,\theta^*\in\widehat{\Theta}_n\,\big)\,=\,1-\frac{q}{m}$$

for finite samples. Parameters m and q are under our control. Note that  $||S_0(\hat{\theta}_n)||^2 = 0$ , thus  $\hat{\theta}_n \in \widehat{\Theta}_n$ , assuming it is non-empty.



## Star Convexity

Set  $\mathcal{X} \subseteq \mathbb{R}^d$  is star convex if there is a star center  $c \in \mathbb{R}^d$  with

$$\forall x \in \mathcal{X}, \forall \beta \in [0,1] : \beta x + (1 - \beta) c \in \mathcal{X}.$$

#### Star Convexity of SPS

 $\widehat{\Theta}_n$  is star convex with the LSE,  $\hat{\theta}_n$ , as a star center

Hint  $\widehat{\Theta}_n$  is the union and intersection of ellipsoids containing LSE.



# Strong Consistency

(A1) independence, symmetricity:  $\{w_t\}$  are independent, symmetric (A2) invertibility:  $R_n \triangleq \frac{1}{n} \sum_{t=1}^{n} \varphi_t \varphi_t^{\mathrm{T}}$  is invertible (A3) regressor growth rate:  $\sum_{t=1}^{\infty} \|\varphi_t\|^4 / t^2 < \infty$ (A4) noise moment growth rate:  $\sum_{t=1}^{\infty} (\mathbb{E}[w_t^2])^2 / t^2 < \infty$ (A5) Cesàro summability:  $\lim_{t \to \infty} R_n = R$ , which is positive definite

#### Strong Consistency of SPS

$$\mathbb{P}\left(\bigcup_{k=1}^{\infty}\bigcap_{n=k}^{\infty}\left\{\widehat{\Theta}_{n}\subseteq B_{\varepsilon}(\theta^{*})
ight\}
ight)=1,$$

where  $B_{\varepsilon}(\theta^*) \triangleq \{ \theta \in \mathbb{R}^d : \|\theta - \theta^*\| \leq \varepsilon \}$  is a norm ball.



## Ellipsoidal Outer Approximation

The reference paraboloid can be rewritten as

$$\|S_0(\theta)\|^2 = (\theta - \hat{\theta}_n)^{\mathrm{T}} R_n(\theta - \hat{\theta}_n).$$

From which an alternative description of the confidence region is

$$\widehat{\Theta}_n \subseteq \Big\{ \theta \in \mathbb{R}^d : (\theta - \widehat{\theta}_n)^{\mathrm{T}} \mathcal{R}_n (\theta - \widehat{\theta}_n) \leq \mathbf{r}(\theta) \Big\},\$$

where  $r(\theta)$  is the *q*th largest value of  $\{||S_i(\theta)||^2\}_{i\neq 0}$ .

#### Ellipsoidal Outer Approximation

$$\widehat{\Theta}_n \subseteq \left\{ \theta \in \mathbb{R}^d \, : \, (\theta - \hat{\theta}_n)^{\mathrm{T}} \mathcal{R}_n (\theta - \hat{\theta}_n) \leq r^* \right\}$$

Where  $r^*$  can be efficiently computed by a semi-definite program.



## Undermodelling

Assume we are given a (finite) sample of input and output data,  $\{u_t\}$ ,  $\{y_t\}$ , which we model with an FIR system

$$\widehat{y}_t(\theta) \triangleq \varphi_t^{\mathrm{T}} \theta + w_t,$$

where  $\varphi_t \triangleq [u_{t-1}, \ldots, u_{t-d}]^\top$ 

#### The true data generation system

$$y_t = \varphi_t^\top \theta^* + \frac{\mathbf{e}_t}{\mathbf{e}_t} + \mathbf{n}_t,$$

where  $e_t$  is an extra component that can depend on all past inputs  $u_{t-d-1}, u_{t-d-2}, \ldots$  and on all past noises  $n_{t-1}, n_{t-2} \ldots$ 

If  $\{e_t\}$  are nonzero, then the SPS confidence regions will still (almost surely) shrink, but around a wrong parameter value.



## SPS with Undermodelling Detection

UD-SPS is obtained from SPS by replacing  $\{S_i(\theta)\}$  with

$$\begin{aligned} Q_{0}(\theta) &\triangleq \begin{bmatrix} R_{n} & B_{n} \\ B_{n}^{\top} & D_{n} \end{bmatrix}^{-\frac{1}{2}} \frac{1}{n} \sum_{t=1}^{n} \begin{bmatrix} \varphi_{t} \\ \psi_{t} \end{bmatrix} (y_{t} - \varphi_{t}^{\top} \theta), \\ Q_{i}(\theta) &\triangleq \begin{bmatrix} R_{n} & B_{n} \\ B_{n}^{\top} & D_{n} \end{bmatrix}^{-\frac{1}{2}} \frac{1}{n} \sum_{t=1}^{n} \alpha_{i,t} \begin{bmatrix} \varphi_{t} \\ \psi_{t} \end{bmatrix} (y_{t} - \varphi_{t}^{\top} \theta), \end{aligned}$$

where  $\psi_t$  is a vector that includes *s* extra input values preceding the  $\hat{n}_b$  that are included in  $\varphi_t$ ,  $\psi_t \triangleq [u_{t-d-1}, \dots, u_{t-d-s}]^\top$ , and

$$B_n \triangleq \frac{1}{n} \sum_{t=1}^n \varphi_t \psi_t^\top, \qquad \qquad D_n \triangleq \frac{1}{n} \sum_{t=1}^n \psi_t \psi_t^\top.$$



# The Connection of UD-SPS and SPS

The connection of UD-SPS and SPS can be stated as

#### Reducing UD-SPS to SPS

The UD-SPS region,  $\widehat{\Theta}_n^{\circ}$ , for estimating  $\theta^* \in \mathbb{R}^d$  can be interpreted as the restriction to a *d*-dimensional space of a standard SPS region,  $\widehat{\Theta}'_n$ , that lives in the domain  $\{\theta' \in \mathbb{R}^{d+s}\}$ .

 $\mathbb{R}^{d+s}$  is the *d*-dimensional identification space augmented with *s* extra components:  $\widehat{\Theta}_n^{o}$  can be identified with the first *d* components of the set  $\widehat{\Theta}'_n \cap (\mathbb{R}^d \times \{0\}^s)$ .



# UD-SPS with Correct System Specifications

Theorem (Exact Confidence of UD-SPS)

If the FIR system is correctly specified, then

$$\mathbb{P}\{\theta^*\in\widehat{\Theta}_n^o\}=1-q/m.$$

### Theorem (Strong Consistency of UD-SPS)

If the FIR system is correctly specified, then (under some technical conditions) for all  $\varepsilon > 0$ , we have that

$$\mathbb{P}\left[\bigcup_{\bar{n}=1}^{\infty}\bigcap_{n=\bar{n}}^{\infty}\left\{\widehat{\Theta}_{n}^{o}\subseteq B_{\varepsilon}(\theta^{*})\right\}\right]=1,$$

where  $B_{\varepsilon}(\theta^*)$  denotes an  $\varepsilon$ -ball centred around  $\theta^*$ .



# UD-SPS in the Presense of Undermodelling

#### Theorem (Undermodelling Detection)

Assume that the system is undermodelled, that is  $\{e_t\}$  are nonzero (and some technical conditions hold). With the notations

$$\bar{R}' \triangleq \lim_{n \to \infty} \begin{bmatrix} R_n & B_n \\ B_n^\top & D_n \end{bmatrix}, \quad \bar{E}' \triangleq \lim_{n \to \infty} \frac{1}{n} \sum_{t=1}^n \begin{bmatrix} \varphi_t \\ \psi_t \end{bmatrix} \mathbb{E}[e_t],$$

if the following detectability condition holds

$$ar{\mathsf{R}}'^{-1}ar{\mathsf{E}}' 
otin \mathbb{R}^{\hat{n}_b} imes \{0\}^s,$$

then

$$\mathbb{P}\left[\bigcup_{\bar{n}=1}^{\infty}\bigcap_{n=\bar{n}}^{\infty}\left\{\widehat{\Theta}_{n}^{o}=\emptyset\right\}\right]=1.$$



## Numerical Experiments

Consider the following ARX(1,1) data generating system

$$y_t = a^* y_{t-1} + b^* u_{t-1} + n_t,$$

with zero initial conditions, where  $a^* = 0.5$  or 0.15 or 0 (see later),  $b^* = 1$ ,  $\{n_t\}$  are i.i.d. Laplacian with mean 0 and variance 0.1. The input signal is generated as  $u_t = 0.75u_{t-1} + v_t$ , where  $\{v_t\}$  are i.i.d. standard normal random variables.

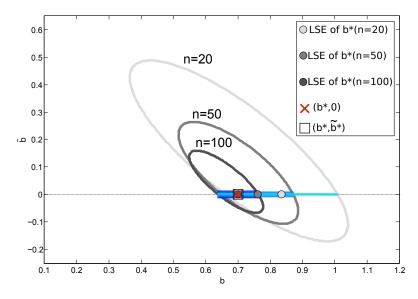
The user-chosen predictor is an FIR(1) model

$$\widehat{y}_t(\theta) = \varphi_t^\top \theta = b \, u_{t-1},$$

that is, the autoregressive part is missing,  $\theta = [b]$  is the model parameter, and  $\varphi_t = [u_{t-1}]$  is the regressor at time *t*.



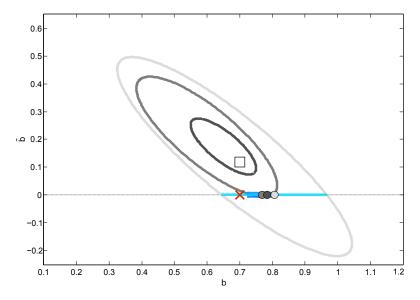
95% UD-SPS Confidence Intervals,  $a^* = 0$ 



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95% UD-SPS Confidence Intervals,  $a^* = 0.15$ 

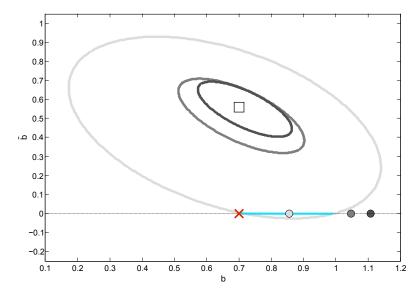


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95% UD-SPS Confidence Intervals,  $a^* = 0.5$ 





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## Summary and Conclusions

- SPS (Sign-Perturbed Sums) is a powerful finite sample system identification method that builds exact, star convex, strongly consistent confidence regions for linear regression problems.
- SPS also has efficient ellipsoidal outer-approximations.
- However, SPS cannot detect if the model class is wrong.
- Here, we suggested an extension of SPS, called UD-SPS, that still guarantees exact and strongly consistent confidence regions if the model order is correctly specified.
- Furthermore, it can detect, in the long run, if the model is undermodelled (detection = empty confidence region).
- There is a strong connection between SPS and UD-SPS.
- The theoretical results were also confirmed by numerical experiments: FIR models of ARX systems were studied.



# Thank you for your attention!

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